

Serial No.: 09/990,127  
Docket No.: PHUS007084US

Response to Notice of Non-Compliant Amendment

### Claim Amendments

This listing of claims will replace all prior versions, and listings, of claims in the application.

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1. (Currently Amended) A medical imaging system for conducting an image-guided medical procedure on a subject, the system comprising:
- a medical imaging apparatus for obtaining volumetric images of the subject;
  - means for planning an interventional procedure on a subject using the volumetric images;
  - a mechanical arm assembly disposed in proximity to the medical imaging apparatus, the mechanical arm assembly comprising a base support, a distal end, a plurality of arm segments, and a plurality of joints between the arm segments for carrying out the interventional procedure; and
  - an end-effector disposed at the distal end of the mechanical arm assembly, the end-effector comprising gripping means for selectively gripping and releasing a surgical instrument during the interventional procedure with a gripping force ranging from zero to a force which prevents relative movement between the gripping means and the surgical instrument.
2. (Original) A medical imaging system according to claim 1 wherein the end-effector further comprises:
- a first finger portion having a first gripping surface;
  - a second finger portion having a second gripping surface, the first and second gripping surfaces being opposed to one another for applying a gripping force to the surgical instrument;
  - a first surgical instrument guide disposed on the first finger portion and extending towards the second finger portion; and
  - a second surgical instrument guide disposed on the second finger portion and extending towards the first finger portion.

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3. (Original) A medical imaging system according to claim 2 further comprising incremental movement means for incrementally inserting the surgical instrument along a trajectory into the subject.

4. (Original) A medical imaging system according to claim 3 wherein the trajectory is linear.

65. (Presently Renumbered) A medical imaging system according to claim 2 wherein the gripping force has a magnitude that allows the surgical instrument to be manually inserted into the subject.

76. (Presently Renumbered) A medical imaging system according to claim 2 wherein the first surgical instrument guide applies a first force to the surgical instrument in a direction perpendicular to the first gripping surface and the second surgical instrument guide applies a second force to the surgical instrument in a direction perpendicular to the second gripping surface.

87. (Presently Renumbered) A medical imaging system according to claim 76 wherein the first force and the second force are substantially zero.

98. (Presently Renumbered) A method of conducting an image-guided medical procedure on a subject, the method comprising:

generating at least one volumetric image of the subject;

planning an interventional procedure on the subject using the at least one volumetric image;

gripping a surgical instrument with an end-effector, the end-effector being disposed at a distal end of a mechanical arm assembly;

moving the surgical instrument into the subject along a trajectory in accordance with the planned interventional procedure using the mechanical arm assembly; and

releasing the surgical instrument.

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~~109~~. (Presently Renumbered) A method of conducting an image-guided medical procedure according to claim ~~9-8~~ further comprising the steps of:

- moving the end-effector away from the subject;
- regripping the surgical instrument; and
- moving the surgical instrument further along the trajectory.

~~110~~. (Presently Renumbered) A method of conducting an image-guided medical procedure according to claim ~~10-9~~ wherein the trajectory is linear.

~~121~~. (Presently Renumbered) A method of conducting an image-guided medical procedure according to claim ~~9-8~~ wherein the step of gripping comprises the steps of:

- applying a gripping force to the surgical instrument using a first gripping surface disposed on a first finger portion of the end-effector and a second gripping surface disposed on a second finger portion of the end-effector; and
- stabilizing the surgical instrument using a first instrument guide disposed on the first finger portion and a second instrument guide disposed on the second finger portion.

~~1312~~. (Presently Renumbered) A method of conducting an image-guided medical procedure according to claim ~~12-11~~ wherein the step of stabilizing the surgical instrument has a stabilizing force in a direction perpendicular to the first and second gripping surfaces associated therewith.

~~1413~~. (Presently Renumbered) A method of conducting an image-guided medical procedure according to claim ~~13-12~~ wherein the stabilizing force is substantially zero.

~~1514~~. (Presently Renumbered) A medical imaging system comprising:

- imaging means for generating at least one volumetric image of a subject;
- planning means for planning an interventional procedure on the subject;

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a mechanical arm assembly disposed in proximity to the imaging means, the mechanical arm assembly comprising a base support, a plurality of arm segments, a plurality of joints, and a distal end;

an end-effector disposed at the distal end of the mechanical arm assembly, the end-effector comprising:

a first finger portion having a first gripping surface;

a second finger portion having a second gripping surface, the first and second gripping surfaces being opposed to one another for applying a gripping force to a surgical instrument;

a first surgical instrument guide disposed on the first finger portion and extending perpendicularly to the first gripping surface; and

a second surgical instrument guide disposed on the second finger portion and extending perpendicularly to the second gripping surface.

4615. (Presently Renumbered) A medical imaging system according to claim 15-14 further comprising a mechanical arm controller for controlling the mechanical arm such that the surgical instrument moves along a path in accordance with the planned interventional procedure.

4716. (Presently Renumbered) A medical imaging system according to claim 46-15 wherein the path comprises a linear trajectory into the subject.

4817. (Presently Renumbered) A medical imaging system according to claim 17-16 wherein the movement of the surgical instrument along the path includes relative movement between the surgical instrument and the end-effector along the linear trajectory.

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4918. (Presently Renumbered) A medical imaging system according to claim 18-17 further comprising position tracking means for tracking a position of the surgical instrument.

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2019. (Presently Renumbered) A medical imaging system according to claim 15-14 wherein the first surgical instrument guide comprises a first and second prong, the first and second prongs extending past the first gripping surface and the second surgical instrument guide comprises a third and fourth prong, the third and fourth prongs extending past the second gripping surface.

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